

1.65V to 3.6V

±2.4mT(Typ)

0.4mT(Typ)

50ms(Typ)

4.4µA (Typ)

CMOS

Omnipolar Detection Hall IC

(Dual Outputs for both S and N Pole Polarity Detection)

BU52272NUZ

General Description

The BU52272NUZ is omnipolar Hall IC incorporating a polarity determination circuit that enables separate operation (output) of both the South and North poles.

This Hall IC product can be in tablets, smart phones, and other applications in order to detect open and close of the cover.

And this Hall IC product can be in digital video cameras and other applications involving display panels in order to detect the front/back location or determine the rotational direction of the panel.

Features

- Omnipolar Detection (Polarity Detection for both S and N Poles with Separate. Dual Outputs)
- Micro Power Operation (Small Current Using Intermittent Operation Method)
- Ultra-small Outline Package
- Polarity Judgment and Separate Output on both Poles

(OUT1=S-pole Output; OUT2=N-pole Output)

Applications

Tablets, Smart Phones, Notebook Computers, Digital Video Cameras, Digital Still Cameras, etc.

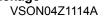
Typical Application Circuit, and Block Diagram

Key Specifications

- V_{DD} Voltage Range:
- Operate Point:
- Hysteresis: Period: Supply Current (AVG):
- Output Type:
 - **Operating Temperature Range:** -40°C to +85°C

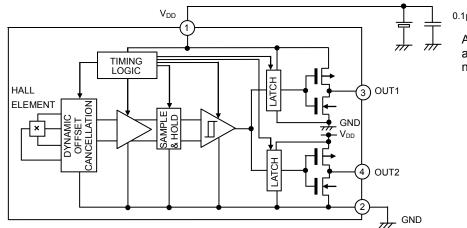
Package

W(Typ) x D(Typ) x H(Max)



1.10mm x 1.40mm x 0.40mm





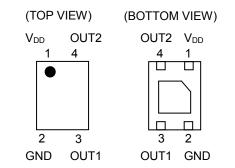
0.1µF

Adjust the bypass capacitor value as necessary, according to voltage noise conditions, etc.

Pin Descriptions

Pin No.	Pin Name	Function
1	V _{DD}	Power supply
2	GND	Ground
3	OUT1	Output (Detect the south pole)
4	OUT2	Output (Detect the north pole)

Pin Configurations



OProduct structure : Silicon monolithic integrated circuit OThis product has no designed protection against radioactive rays

Contents

General Description	1
Features	1
Applications	1
Key Specifications	1
Package	1
Typical Application Circuit, and Block Diagram	1
Pin Descriptions	1
Pin Configurations	1
Absolute Maximum Ratings	3
Thermal Resistance	3
Recommended Operating Conditions	4
Magnetic, Electrical Characteristics	4
Measurement Circuit	5
Typical Performance Curves	6
Figure 5. Operate Point, Release Point vs Ambient Temperature	6
Figure 6. Operate Point, Release Point vs Supply Voltage	6
Figure 7. Period vs Ambient Temperature	6
Figure 8. Period vs Supply Voltage	6
Figure 9. Supply Current vs Ambient Temperature	7
Figure 10. Supply Current vs Supply Voltage	7
Description of Operations	8
Intermittent Operation at Power ON	11
Magnet Selection	11
Position of the Hall Element	11
I/O Equivalence Circuit	11
Operational Notes	12
Ordering Information	14
Marking Diagrams	14
Physical Dimension, Tape and Reel Information	15
Revision History	16

Absolute Maximum Ratings (Ta = 25°C)

Parameter	Symbol	Rating	Unit
Power Supply Voltage	V _{DD}	4.5	V
Output Current	I _{OUT}	±0.5	mA
Operating Temperature Range	T _{opr}	-40 to +85	°C
Storage Temperature Range	T _{stg}	-40 to +125	°C
Maximum Junction Temperature	T _{jmax}	125	°C

Caution:Operating the IC over the absolute maximum ratings may damage the IC. The damage can either be a short circuit between pins or an open circuit between pins and the internal circuitry. Therefore, it is important to consider circuit protection measures, such as adding a fuse, in case the IC is operated over the absolute maximum ratings.

Thermal Resistance^(Note 1)

Parameter		Thermal Resistance (Typ)		l lait
Palameter	Symbol	1s ^(Note 3)	2s2p ^(Note 4)	- Unit
VSON04Z1114A				
Junction to Ambient	θ_{JA}	512.5	206.1	°C/W
Junction to Top Characterization Parameter ^(Note 2)	Ψ_{JT}	281	101	°C/W

(Note 1)Based on JESD51-2A(Still-Air)
(Note 2)The thermal characterization parameter to report the difference between junction temperature and the temperature at the top center of the outside surface of the component package.
(Note 3)Using a PCB board based on JESD51-3.

Layer Number of Measurement Board Material		Board Size
Single	FR-4	114.3mm x 76.2mm x 1.57mmt
Тор		
Copper Pattern	Thickness	
Footprints and Traces	70µm	

(Note 4)Using a PCB board based on JESD51-7.

Layer Number of Measurement Board	Material	Board Size			
4 Layers	FR-4	114.3mm x 76.2mm :	x 1.6mmt		
Тор		2 Internal Layers		Bottom	
Copper Pattern	Thickness	Copper Pattern	Thickness	Copper Pattern	Thickness
Footprints and Traces	70µm	74.2mm x 74.2mm	35µm	74.2mm x 74.2mm	70µm

Recommended Operating Conditions (Ta= -40°C to +85°C)

Parameter	Symbol	Min	Тур	Max	Unit
Power Supply Voltage	V _{DD}	1.65	1.80	3.60	V

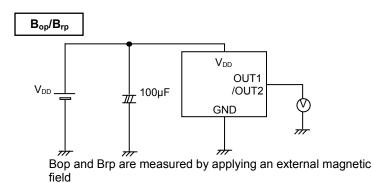
Magnetic, Electrical Characteristics (Unless otherwise specified V_{DD}=1.8V Ta=25°C)

Parameter	Symbol	Min	Тур	Max	Unit	Conditions
On events Daint	BopS	-	2.4	3.2	T	Output: OUT1 (Detect the south pole)
Operate Point	B _{opN}	-3.2	-2.4	-	mT	Output: OUT2 (Detect the north pole)
Release Point	B _{rpS}	1.2	2.0	-	mT	Output: OUT1 (Detect the south pole)
	B _{rpN}	-	-2.0	-1.2	1111	Output: OUT2 (Detect the north pole)
Hysteresis	B _{hysS}	-	0.4	-	mT	
	B _{hysN}	-	0.4	-	1111	
Period	Tp	-	50	100	ms	
Output High Voltage	V _{OH}	V _{DD} -0.2	-	-	V	I _{OUT} =-0.5mA
Output Low Voltage	Vol	-	-	0.2	V	I _{OUT} =+0.5mA
Supply Current	I _{DD}	-	4.4	8	μA	Average

1mT=10Gauss

Positive ("+") polarity flux is defined as the magnetic flux from south pole which is direct toward to the branded face of the sensor. After applying power supply, it takes one cycle of period (T_P) to become definite output.

Measurement Circuit





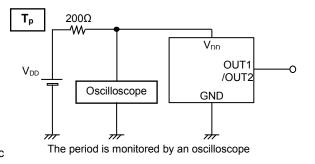


Figure 2. Tp Measurement Circuit

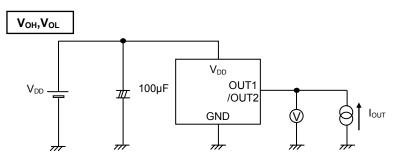


Figure 3. VOH , VOL Measurement Circuit

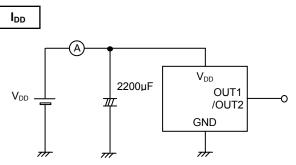
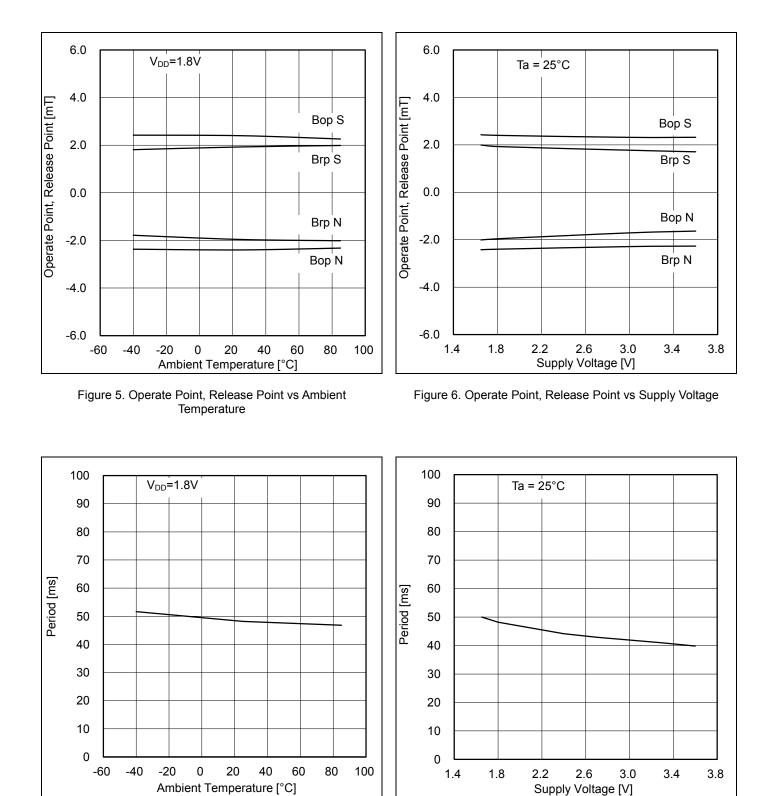


Figure 4. I_{DD} Measurement Circuit

Typical Performance Curves



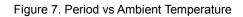


Figure 8. Period vs Supply Voltage

Typical Performance Curves - continued

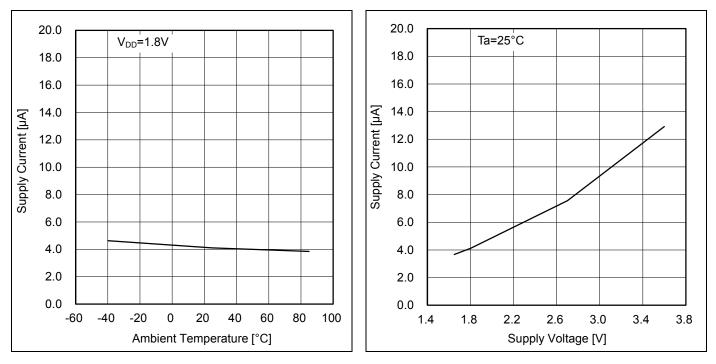
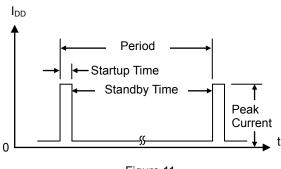


Figure 9. Supply Current vs Ambient Temperature

Figure 10. Supply Current vs Supply Voltage

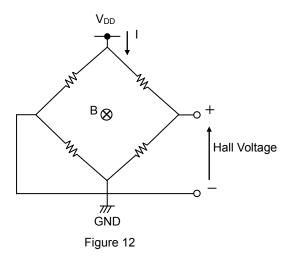
Description of Operations

Micropower Operation (Small Current Consumption Using Intermittent Sensing)





(Offset Cancellation)



The dual output omnipolar detection Hall IC uses intermittent sensing save energy. At startup the Hall elements, amplifier, comparator, and other detection circuits power on and magnetic detection begins. During standby, the detection circuits power off, thereby reducing current consumption. The detection results are held while standby is active, and then output.

> Period: T_p Startup Time: T_p /4096x4 clk Peak Current: 8mA (Reference data, this is not thing guaranteeing.)

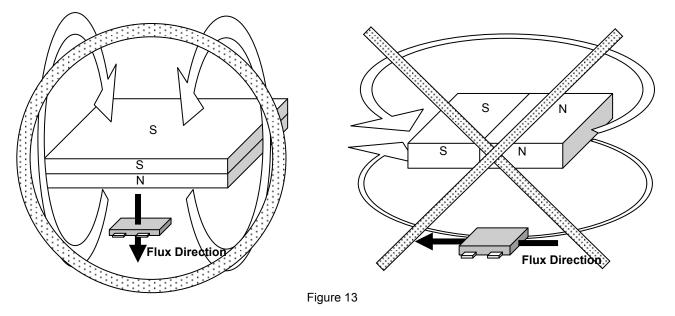
The Hall elements form an equivalent Wheatstone (resistor) bridge circuit. Offset voltage may be generated by a differential in this bridge resistance, or can arise from changes in resistance due to package or bonding stress. A dynamic offset cancellation circuit is employed to cancel this offset voltage.

When the Hall elements are connected as shown in Figure 12 and a magnetic field is applied perpendicular to the Hall elements, a voltage is generated at the mid-point terminal of the bridge. This is known as Hall voltage.

Dynamic cancellation switches the wiring (shown in the figure) to redirect the current flow to a 90° angle from its original path, and thereby cancels the Hall voltage.

The magnetic signal (only) is maintained in the sample/hold circuit during the offset cancellation process and then released.

(Magnetic Field Detection Mechanism)



The Hall IC cannot detect magnetic fields that run horizontal to the package top layer. Be certain to configure the Hall IC so that the magnetic field is perpendicular to the top layer.

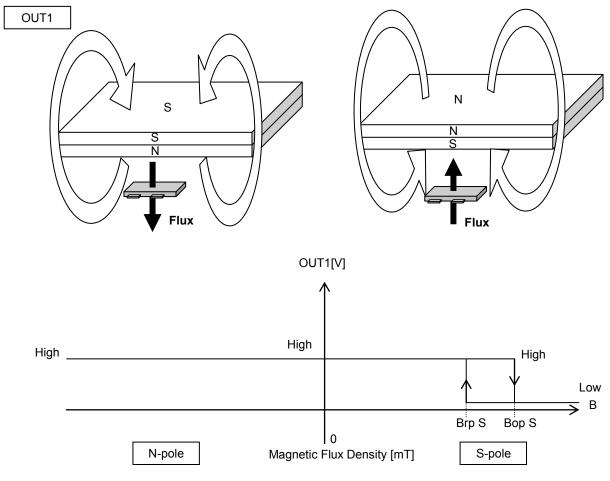


Figure 14. S-pole Detection

The OUT1 pin detects and outputs for the S-pole only. Since the OUT1 pin output is unipolar, the output does not respond to the N-pole.

OUT2

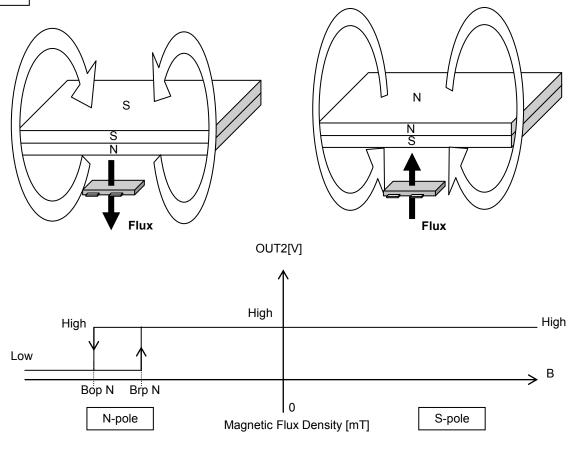


Figure 15. N-pole Detection

The OUT2 pin detects and outputs for the N-pole only. Since the OUT2 pin output is unipolar, the output does not respond to the S-pole.

The dual output omnipolar detection Hall IC detects magnetic fields running perpendicular to the top surface of the package. There is an inverse relationship between magnetic flux density and the distance separating the magnet and the Hall IC: when distance increases magnetic density falls. When it drops below the operate point (Bop), output goes HIGH. When the magnet gets closer to the IC and magnetic density rises to the operate point, the output switches LOW. In LOW output mode, the distance from the magnet to the IC increases again until the magnetic density falls to a point just below Bop, and output returns HIGH. The point where magnetic flux density restores a HIGH output is known as the release point, Brp. This detection and adjustment mechanism is designed to prevent noise, oscillation, and other erratic system operation.

Intermittent Operation at Power ON

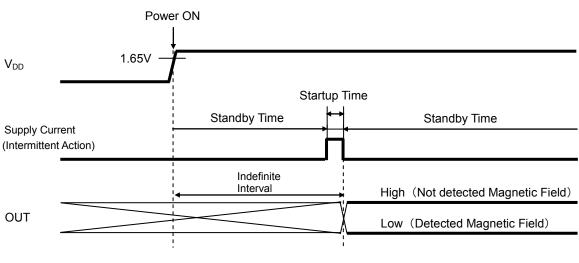


Figure 16

The dual output omnipolar detection Hall IC adopts an intermittent operation method in detecting the magnetic field during startup, as shown in Figure 16. The IC outputs to the appropriate terminal based on the detection result and maintains the output condition during the standby period. The time from power ON until the end of the initial startup period is an indefinite interval, but it cannot exceed the maximum period of 100ms. To accommodate the system design, the Hall IC output read should be programmed within 100ms of power ON, but after the time allowed for the period, ambient temperature, and supply voltage.

Magnet Selection

Neodymium and ferrite are major permanent magnets. Neodymium generally offers greater magnetic power per volume than ferrite, thereby enabling miniaturization of magnet. The larger neodymium magnet is, the stronger magnetic flux density is. And the farther detection distance is, the weaker it is. Therefore the proper size and detection distance of the magnet should be determined according to the sensitivity of Hall IC. To increase the magnet's detection distance, the magnet which is thicker or larger sectional area is used.

Position of the Hall Element

(Reference)

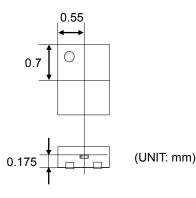


Figure 17

I/O Equivalence Circuit

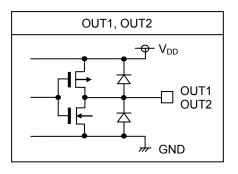


Figure 18

Operational Notes

1. Reverse Connection of Power Supply

Connecting the power supply in reverse polarity can damage the IC. Take precautions against reverse polarity when connecting the power supply, such as mounting an external diode between the power supply and the IC's power supply pins.

2. Power Supply Lines

Design the PCB layout pattern to provide low impedance supply lines. Furthermore, connect a capacitor to ground at all power supply pins. Consider the effect of temperature and aging on the capacitance value when using electrolytic capacitors.

3. Ground Voltage

Ensure that no pins are at a voltage below that of the ground pin at any time, even during transient condition.

4. Ground Wiring Pattern

When using both small-signal and large-current ground traces, the two ground traces should be routed separately but connected to a single ground at the reference point of the application board to avoid fluctuations in the small-signal ground caused by large currents. Also ensure that the ground traces of external components do not cause variations on the ground voltage. The ground lines must be as short and thick as possible to reduce line impedance.

5. Thermal Consideration

Should by any chance the maximum junction temperature rating be exceeded the rise in temperature of the chip may result in deterioration of the properties of the chip. In case of exceeding this absolute maximum rating, increase the board size and copper area to prevent exceeding the maximum junction temperature rating.

6. Recommended Operating Conditions

These conditions represent a range within which the expected characteristics of the IC can be approximately obtained. The electrical characteristics are guaranteed under the conditions of each parameter.

7. Inrush Current

When power is first supplied to the IC, it is possible that the internal logic may be unstable and inrush current may flow instantaneously due to the internal powering sequence and delays, especially if the IC has more than one power supply. Therefore, give special consideration to power coupling capacitance, power wiring, width of ground wiring, and routing of connections.

8. Operation Under Strong Electromagnetic Field

Operating the IC in the presence of a strong electromagnetic field may cause the IC to malfunction.

9. Testing on Application Boards

When testing the IC on an application board, connecting a capacitor directly to a low-impedance output pin may subject the IC to stress. Always discharge capacitors completely after each process or step. The IC's power supply should always be turned off completely before connecting or removing it from the test setup during the inspection process. To prevent damage from static discharge, ground the IC during assembly and use similar precautions during transport and storage.

10. Inter-pin Short and Mounting Errors

Ensure that the direction and position are correct when mounting the IC on the PCB. Incorrect mounting may result in damaging the IC. Avoid nearby pins being shorted to each other especially to ground, power supply and output pin. Inter-pin shorts could be due to many reasons such as metal particles, water droplets (in very humid environment) and unintentional solder bridge deposited in between pins during assembly to name a few.

Operational Notes – continued

11. Unused Input Pins

Input pins of an IC are often connected to the gate of a MOS transistor. The gate has extremely high impedance and extremely low capacitance. If left unconnected, the electric field from the outside can easily charge it. The small charge acquired in this way is enough to produce a significant effect on the conduction through the transistor and cause unexpected operation of the IC. So unless otherwise specified, unused input pins should be connected to the power supply or ground line.

12. Regarding the Input Pin of the IC

In the construction of this IC, P-N junctions are inevitably formed creating parasitic diodes or transistors. The operation of these parasitic elements can result in mutual interference among circuits, operational faults, or physical damage. Therefore, conditions which cause these parasitic elements to operate, such as applying a voltage to an input pin lower than the ground voltage should be avoided. Furthermore, do not apply a voltage to the input pins when no power supply voltage is applied to the IC. Even if the power supply voltage is applied, make sure that the input pins have voltages within the values specified in the electrical characteristics of this IC.

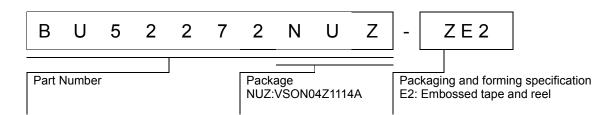
13. Ceramic Capacitor

When using a ceramic capacitor, determine the dielectric constant considering the change of capacitance with temperature and the decrease in nominal capacitance due to DC bias and others.

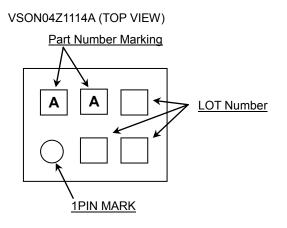
14. Area of Safe Operation (ASO)

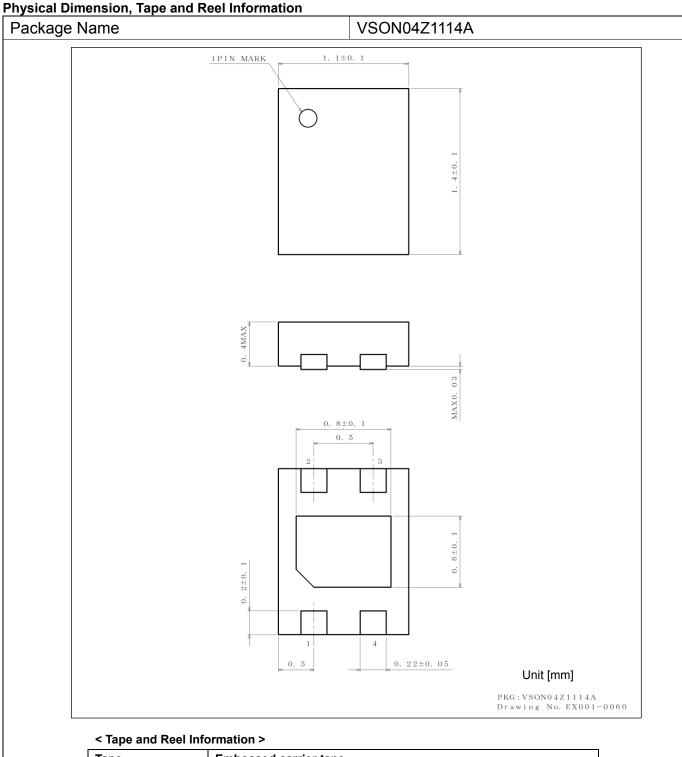
Operate the IC such that the output voltage, output current, and the maximum junction temperature rating are all within the Area of Safe Operation (ASO).

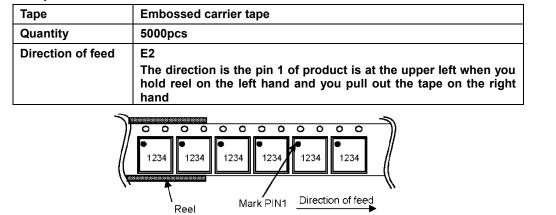
Ordering Information



Marking Diagrams







Revision History

Date	Revision	Changes
1.Mar.2016	001	New Release
24.May.2016	002	P3. Modified Absolute Maximum Ratings and Correction of error in Thermal Resistance

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JÁPAN	USA	EU	CHINA
CLASSⅢ	CLASSⅢ	CLASS II b	CLASSII
CLASSⅣ	CLASSII	CLASSⅢ	CLASSI

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